PEGAPCRSA80V1_2019^{Q&As}

Pega Certified Robotics System Architect 80V1 2019

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QUESTION 1

You are evaluating business requirements and reviewing each adapter in a project.

Prior to interrogating the application, what three actions do you perform during application discovery? (Choose three.)

A. Identify the technology on which the application is built (web, Windows, text).

B. Verify the match rules on all interrogated controls.

C. Verify the interactions between all applications in the solution.

D. Verify the number of application instances accessed by the user at the same time.

E. Verify how the application launches outside of Pega Robot Studio.

Correct Answer: BCD

Reference: http://help.openspan.com/191/Adapters_Interrogation/interrogator_and_match_rules2.htm

QUESTION 2

DRAG DROP

In the Answer Area, drag each use case on the left to the correct Toolbox item.

Select and Place:

Answer Area

	Use Case	Toolbox item
Used to add custom log entries to the RuntimeLog.txt file and the Output window.		DiagnosticLog
Used to allow two concurrent threads to communicate and to synchronize events.		LogController
Holds a value which may be increased or decreased by calling a method.		Counter
Used to enable or disable diagnostic logging to the RuntimeLog.txt file.		Signal
Used to permit conditional execution based on the value of a variable.		Switch

Correct Answer:

Answer Area

Use Case	Toolbox item
Used to add custom log entries to the RuntimeLog.txt file and the Output window.	DiagnosticLog
Used to allow two concurrent threads to communicate and to synchronize events.	LogController
Holds a value which may be increased or decreased by calling a method.	Counter
Used to permit conditional execution based on the value of a variable.	Signal
Used to enable or disable diagnostic logging to the RuntimeLog.txt file.	Switch

QUESTION 3

You have completed your solution design. The customer installed the Pega Robot Runtime software on the agent\\'s desktop. The customer is ready to unit test your solution, but wants the Runtime executable to automatically launch the new robotics solution.

How do you fulfill this request?

A. Edit the StartupProject key in the RuntimeConfig.xml by setting the value to the file location of the .openspan file.

B. Edit the StartupProject key in the StudioConfig.xml by setting the value to the file location of the .openspan file.

C. Edit the StartProject key in the StudioConfig.xml by setting the value to the file location of the .manifest file.

D. Edit the StartProject key in the RuntimeConfig.xml by setting the value to the file location of the .diagnostics file.

Correct Answer: A

Reference: http://help.openspan.com/80/Platform_Configuration/RuntimeConfigXML.htm

QUESTION 4

DRAG DROP

When debugging an automation, you have three function keys to use for navigating the breakpoints. In the Answer Area, drag each navigation rule on the left to its correct function key.

Select and Place:

Answer Area

	Navigation Rule	Function Key
Move execution to the next event or data link.		F10
Move execution to the next event link.		F11
Continue the execution until the next breakpoint is reached.		F5

Correct Answer:

Answer Area

	Navigation Rule	Function Key
	Move execution to the next event link.	F10
	Move execution to the next event or data link.	F11
	Continue the execution until the next breakpoint is reached.	F5

Reference: http://help.openspan.com/52/Diagnostics/Break_Points.htm

QUESTION 5

Which two of the following Tool Windows are used in Pega Robot Studio? (Choose two.)

A. Designer windows

B. Solution Explorer

C. Object Explorer

D. Menu toolbar

Correct Answer: AD